

Journal of Heat and Mass Transfer Research

Journal homepage: http://jhmtr.semnan.ac.ir



Unsteady Magnetohydrodynamic Mixed Convection Flow over a Rotating Sphere with Sinusoidal Mass Transfer

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PAPER INFO

Paper history: Received: 2021-03-16 Received: 2023-01-04 Accepted: 2023-01-10

Keywords: Boundary layer; Heat transfer; Variable properties; Mixed convection; MHD; Non-uniform mass transfer; Non-similar solution; Rotating sphere.

ABSTRACT

This paper investigates the unsteady magnetohydrodynamic (MHD) mixed convective fluid flow over a rotating sphere. An implicit finite difference scheme, together with quasilinearization, is used to find non-similar solutions for the governing equations. The impact of variable physical properties and viscous dissipation are included. It is observed that the skin friction coefficient in the axial direction and the heat transfer coefficient are increasing with an increase in MHD, mixed convection and rotation parameters and with time, whereas the effect is just the opposite for the skin friction coefficient in the rotational direction. The nonuniform slot suction(injection) and the slot movement influence the point of vanishing skin friction to move in the axial direction downstream (upstream).

DOI: <u>10.22075/jhmtr.2023.22926.1339</u>

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1. Introduction

The investigation of boundary layer flow and heat transfer over rotating bodies of revolution has several technical applications, including fiber coating, re-entry missile design, and rotary machine design [1]. The sphere being a well-renowned geometry used in engineering devices, many times the motion of models spherical endure rotation and suction/blowing. As a result, understanding the influence of rotation as well as mass transfer on flow over a spinning sphere is critical. Kreith et al. [2] have investigated convection heat transport and flow phenomena and Lee et al. [3] have incorporated forced flow over rotating spheres. The effects of surface blowing on the above-described geometry were investigated by Niazmand and Renksizbulut [4]. Recently, Safarzadeh and Brahimi [5] have established the flow phenomena over the rotating sphere in porous media. Many researchers have worked on flows over rotating bodies such as cylinders, disks, and cones, under different circumstances [6-8].

There is a substantial variation in fluid properties owing to the presence of a temperature gradient across a fluid medium. This temperature variation may be due to heat transfer when the fluid and the surface have dissimilarity in temperature or when there is a loss of heat present in the form of latent energy upon its liberation [9]. Together with these varying physical properties, the process of heat transfer for a variety of objects has already been thoughtfully analyzed by a significant number of researchers [10-16].

The mass transfer through a wall slot holds several tremendous practical implications in thermal protection, fuel injecting system of ramjets, drying theory, galvanizing the innermost section of the boundary layer in adverse pressure gradients, and reducing skin friction on high-speed aircraft [17]. Uniform suction (injection) creates discontinuities at the ends of the slot. An ultimate solution to overcome this is by implementing а non-uniform suction(injection), as discussed by Roy and Nath in [18]. Since then, several researchers have carried out the work on the impact of the non-uniform mass

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transfer over various two-dimensional axisymmetric bodies [12,13,15-17,19] and that over rotating bodies [11,14,21].

The boundary-layer flows are found to be both unsteady and non-similar in nature. The unsteadiness and non-similarity that occur may be due to the body's curvature or the velocity profiles at the boundary or the surface mass transfer, or perhaps an amalgamation of all the factors mentioned above. A vast majority of the researchers restrained their works to unsteady self-similar flows or steady non-similar flows due to mathematical complexities. A brief review of methods to find a non-similar solution for steady flows and the references of apposite works done up till 1967 has been stated in [21]. In the past two decades, many researchers worked on a non-similar solution for steady/unsteady flows over various shapes of nonspinning bodies [12,13,15,17,22-24]. In the case of rotating bodies, authors in [25-27] presented selfsimilar solutions for steady/unsteady flow over a rotating sphere, whereas in [10,11,28] have given nonsimilar solutions.

The inclusion of the effect of MHD and mixed convection has received keen attention recently. An enormous number of researchers have analyzed the effect of mixed convection on steady or unsteady fluid flow over various non-spinning bodies [17,29-32] and over rotating bodies [1,33-39]. On the other hand, the effect of MHD on steady or unsteady fluid flow over two-dimensional axisymmetric bodies has been observed by Sathyakrishna et al. [40], and over a rotating sphere has been studied in [10,27,41,42]. The above studies were focused on analyzing the flow problem with either mixed convection or magnetic field. The combined effect of MHD and mixed convection on a steady fluid flow over a sphere, rotating sphere, wedge, and the vertical elastic sheet has been studied in [11,12,19,43], respectively. Recently, Ghani and Rumite [44] have worked on the MHD mixed convection flow over a solid sphere by using the Keller-box method.

Further taking unsteadiness into account, Chamkha et al. [22,45] showed the combined effect of MHD and mixed convection of fluid flow at the forward stagnation region of a rotating sphere in the presence of chemical reaction and heat source and at different wall conditions. Mahdy et al. [26] have investigated the same with an analysis of entropy generation due to non-Newtonian Casson nanofluid. Recently, Jenifer et al. [46] obtained non-similar solutions for an unsteady MHD mixed convective flow over a stationary sphere with mass transfer. Gul et al. [47] have worked on the stagnation point flow of blood-based hybrid nanofluid over a rotating sphere with the inclusion of mixed convection and a time-dependent magnetic field. Considering an impulsively rotating sphere, Calabretto et al. [48] have explored the effects of unsteadiness and Mahdy et al. [49] have further extended the study to

homogeneous - heterogeneous reactions in MHD mixed nanofluid flow. Numerous writers have recently researched flow through spinning spheres while taking into account phenomena like double diffusive convection, magnetophoresis and joule heating. [50-52].

From the literature review, the sinusoidal mass transfer in the case of unsteady rotating sphere is not studied so far. The novelty of this work lies in finding non-similar solutions under the combined effects of the following circumstances.

- Temperature-dependent viscosity and Prandtl number
- MHD mixed convective flow over a rotating sphere
- Unsteady (accelerating) flow model
- Sinusoidal suction/injection through a slot
- Viscous dissipation and Joule heating

This study finds its applications in flows over rotating axisymmetric bodies where the flow is time dependent and the boundary layer can be controlled by implementing the above-mentioned factors. The governing equations are transformed with the help of nonsimilar transformations and the corresponding nonsimilar solutions are obtained by using implicit finite difference method along with quasilinearization technique. Important flow parameters such as skin friction and heat transfer coefficients are analyzed for various values of the effects taken into account. The fluid considered here is water due to its extreme practical applications in engineering.

2. Mathematical Formulation

The coordinate system and flow model over a heated sphere is presented in Figure 1. It is assumed that the sphere rotates with angular velocity $\Omega(t)$ (a time-dependent function) with its rotation axis parallel to $u_e(x, t)$. A constant magnetic field B_0 is enforced perpendicular to the sphere's surface. The mixed convective flow is supposed to be in the upward direction, and the sphere rotates in y –direction.



Figure 1. Flow model

The variation of temperature between the free stream and the sphere's surface is assumed to be less than 40°C. Within this temperature limit considered, the properties of water, such as density (ρ) and specific heat (c_p) vary up to a maximum of 1%, and this minute variation allows the use of ρ and c_p as constants. On the other hand, properties such as viscosity (μ) and thermal conductivity (k) vary significantly with temperature, and so does the Prandtl number (Pr). Both μ and Pr have an inverse linear relationship with temperature as specified in [23].

$$\mu = \frac{1}{(a+bT)} \text{ and } Pr = \frac{1}{(c+dT)}$$
(1)

with a = 53.41, b = 2.43, c = 0.068, d = 0.004. (2)

The boundary layer flow is governed by the following equations:

$$(ru)_x + (rw)_z = 0$$
 (3)

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$$u_{t} + uu_{x} + wu_{z} - \frac{v^{2}}{r}r_{x} = (u_{e})_{t} + u_{e}(u_{e})_{x}$$

+ $\frac{1}{\rho}(\mu u_{z})_{z} + g\beta(T - T_{\infty})\sin\left(\frac{x}{R}\right) - \frac{\sigma B_{0}^{2}}{\rho}(u - u_{e})$ (4)

$$v_t + uv_x + wv_z + \frac{uv}{r}r_x = \frac{1}{\rho}(\mu v_z)_z - \frac{\sigma B_0^2}{\rho}v$$
 (5)

$$T_{t} + uT_{x} + wT_{z} = \frac{1}{\rho} \left(\frac{\mu}{Pr} T_{z}\right)_{z} + \frac{\mu}{\rho c_{p}} (u_{z}^{2} + v_{z}^{2}) + \frac{\sigma B_{0}^{2}}{\rho c_{p}} (u^{2} + v^{2} - u_{e}u)$$
(6)

Initial conditions:

$$u(x, z, 0) = u_i(x, z), \quad v(x, z, 0) = v_i(x, z), w(x, z, 0) = w_i(x, z), \quad T(x, z, 0) = T_i(x, z).$$
(7)

Boundary conditions:

$$u(x, 0, t) = 0, u(x, \infty, t) = u_e(x, t),$$

$$v(x, 0, t) = \Omega(t)r(x), w(x, 0, t) = w_w(x, t),$$

$$T(x, 0, t) = T_w = \text{constant},$$

$$T(x, \infty, t) = T_{\infty} = \text{constant}.$$
(8)

The transformations to convert the equations (4)-(6) and the conditions (7) and (8) into a nondimensional form are as follows:

$$\begin{split} \xi &= \int_{0}^{x} \frac{U}{u_{\infty}} \left(\frac{x}{R}\right)^{2} d\left(\frac{x}{R}\right), \bar{t} = \frac{3}{2} Re\left(\frac{\mu_{e}}{\rho R^{2}}\right) t, \\ \eta &= \left(\frac{U}{u_{\infty}}\right) \left(\frac{Re}{2\xi}\right)^{1/2} \left(\frac{r}{R}\right) \left(\frac{z}{R}\right), Re = \frac{u_{\infty}R}{\nu}, \\ \varphi(\bar{t}) &= 1 + \epsilon \bar{t}^{2}, \epsilon = 0.25, G = \frac{T - T_{w}}{T_{\infty} - T_{w}}, \\ \psi(x, z, t) &= u_{\infty} R\phi(\bar{t}) \left(\frac{2\xi}{Re}\right)^{1/2} f(\xi, \eta, \bar{t}), \\ \Omega &= \Omega_{0}\phi(\bar{t}), u = \left(\frac{R}{r}\right)\psi_{z}, \\ v &= \Omega_{0}r(x)\phi(\bar{t})S(\xi, \eta, \bar{t}), w = -\left(\frac{R}{r}\right)\psi_{x}. \end{split}$$
(9)

The above transformations satisfy (3) identically, and the non-dimensional forms of (4)-(6) are given below

$$(NF_{\eta})_{\eta} + \phi [fF_{\eta} + \chi(1 - F^{2})] -P[F_{\bar{t}} - \phi^{-1}\phi_{\bar{t}}(1 - F)] + \alpha(\xi)\phi S^{2} + \phi^{-1}\lambda S_{1}(\xi)(1 - G) + MP(1 - F) = 2\xi\phi (FF_{\xi} - f_{\xi}F_{\eta})$$
 (10)

$$(NS_{\eta})_{\eta} + \phi f S_{\eta} - P[S_{\bar{t}} + \phi^{-1}\phi_{\bar{t}}S]$$

$$-\alpha_{1}(\xi)\phi FS - MPS = 2\xi\phi(FS_{\xi} - f_{\xi}S_{\eta})$$

$$(11)$$

$$\left(\frac{1}{Pr}NG_{\eta}\right)_{\eta} + \phi f G_{\eta} - PG_{\bar{t}}$$

$$+N\left(\frac{u_{e}}{u_{\infty}}\right)^{2} Ec[F_{\eta}^{2} + BS_{\eta}^{2}] + PEcM\left(\frac{u_{e}}{u_{\infty}}\right)^{2} \qquad (12)$$

$$(F^{2} + BS^{2} - F) = 2\xi\phi(FG_{\xi} - f_{\xi}G_{\eta})$$

with the boundary conditions

$$F(\xi, 0, \bar{t}) = 0, \quad F(\xi, \infty, \bar{t}) = 1,$$

$$S(\xi, 0, \bar{t}) = 1, \quad S(\xi, \infty, \bar{t}) = 0,$$

$$G(\xi, 0, \bar{t}) = 0, G(\xi, \infty, \bar{t}) = 1$$

where
(13)

$$N = \frac{\mu}{\mu_{\infty}} = \frac{a + bT_{\infty}}{a + bT} = \frac{1}{E_{1} + E_{2}G'},$$

$$E_{1} = \frac{a + bT_{w}}{a + bT_{\omega}}, E_{2} = \frac{(T_{\infty} - T_{w})b}{a + bT_{\infty}},$$

$$Pr = \frac{1}{c + dT} = \frac{1}{E_{3} + E_{4}G'},$$

$$E_{3} = c + dT_{w}, E_{4} = (T_{\infty} - T_{w})d,$$

$$\frac{u}{u_{e}} = f_{\eta} = F, u_{e} = U\Phi(\bar{t}),$$

$$Ec = \frac{u_{\infty}^{2}}{c_{p}(T_{\infty} - T_{w})}, f = \int_{0}^{\eta} F d\eta + f_{w},$$

$$\chi = \frac{2\xi dU}{U d\xi}, P = 3\xi \left(\frac{R}{r}\right)^{2} \left(\frac{u_{\infty}}{U}\right)^{2},$$

$$G_{1} = \frac{4\xi dr}{r d\xi}, M = \frac{2}{3} \frac{\sigma B_{0}^{2}R}{\rho \mu_{\infty}},$$

$$S_{1}(\xi) = 2\xi \left(\frac{u_{\infty}}{U}\right)^{3} \left(\frac{R}{r}\right), \lambda = \frac{Gr}{Re^{2}},$$

$$Gr = \frac{g\beta \Delta T_{w}R^{3}}{v_{\infty}^{2}}, v_{\infty} = \frac{\mu_{\infty}}{\rho}, B = \left(\frac{\Omega_{0}r}{U}\right)^{2},$$

$$w = -\left(\frac{r}{R}\right)(2\xi Re)^{-1/2}U\Phi\left[f + 2\xi f_{\xi} + \left(\chi + \frac{\alpha_{1}}{2} - 1\right)\eta F\right],$$

$$f_{w} = -\left(\frac{Re}{2\xi}\right)^{1/2} \phi^{-1} \int_{0}^{x} \frac{w_{w}(x,\bar{t})}{u_{\infty}} \left(\frac{r}{R}\right) d\left(\frac{x}{R}\right)$$

The velocity distribution at the boundary layer's edge is written as,

$$\frac{u_e}{u_{\infty}} = \frac{3}{2} \phi(\bar{t}) \sin \bar{x}, \frac{U}{u_{\infty}} = \frac{3}{2} \sin \bar{x},$$

$$\frac{r}{R} = \sin \bar{x}, \bar{x} = \frac{x}{R}.$$
(15)

Hence ξ , $\beta(\xi)$, $P(\xi)$, $\alpha(\xi)$, $\alpha_1(\xi)$, B and $S_1(\xi)$ can be written as expressions in \bar{x} as follows.

$$\xi = \frac{K_1^2 K_3}{2}, \chi = \frac{2K_3 K_2^{-2}}{3} \cos \bar{x},$$

$$P = \frac{2K_2^{-2} K_3}{3}, \alpha = B\chi, \alpha_1 = 2\chi,$$

$$B = \frac{4}{9} \left(\frac{\Omega_0 R}{u_{\infty}}\right)^2, S_1 = \frac{8K_2^{-2} K_3}{27}$$
where

iere

$$K_1 = 1 - \cos \bar{x}, K_2 = 1 + \cos \bar{x},$$

$$K_3 = 2 + \cos \bar{x}.$$
(17)

The following suction/injection distribution at the wall is taken as a sinusoidal function. It exhibits a nonuniform mass transfer only in the interval $[\bar{x}_0, \bar{x}_0^*]$ which can endure a slow mass transfer at the slot's ends without breaking its continuity. Here, A is the mass transfer parameter with A > 0 indicating suction and A < 0 indicating injection through the slot. The parameter ω^* determines the slot length which is fixed at 2π whenever mass transfer is applied in this paper.

$$w_{w} = \begin{cases} \frac{-2Au_{\infty}}{(Re)^{1/2}} \sin[C(\bar{x}, \bar{x}_{0})], \bar{x} \in [\bar{x}_{0}, \bar{x}_{0}^{*}] \\ 0, & \text{otherwise} \end{cases}$$
(18)

 $\mathcal{C}(\bar{x}, \bar{x}_0) = \omega^* (\bar{x} - \bar{x}_0).$

The value of surface mass transfer f_w is given by

$$f_{w} = \begin{cases} 0, & \bar{x} \leq \bar{x}_{0} \\ \frac{A}{\phi K_{1}} (K_{3})^{-1/2} \zeta(\bar{x}, \bar{x}_{0}) , \bar{x} \in [\bar{x}_{0}, \bar{x}_{0}^{*}] \\ \frac{A}{\phi K_{1}} (K_{3})^{-1/2} \zeta(\bar{x}_{0}^{*}, \bar{x}_{0}) , \text{ otherwise} \end{cases}$$
(19)

$$\zeta(\bar{x}, \bar{x}_0) = \frac{\sin[C(\bar{x}, \bar{x}_0) - \bar{x}] + \sin \bar{x}_0}{(\omega^* - 1)} - \frac{\sin[C(\bar{x}, \bar{x}_0) - \bar{x}] - \sin \bar{x}_0}{(\omega^* + 1)}.$$

It is convenient to write the equations in \bar{x} instead of ξ . \bar{x} and ξ are related by

$$\xi \frac{\partial}{\partial \xi} = Q(\bar{x}) \frac{\partial}{\partial \bar{x}}$$
(20)

where

$$Q(\bar{x}) = \frac{K_3 K_2^{-1}}{3} tan \frac{\bar{x}}{2}$$
(21)

Substituting equations (20) and (21) in the equations (10), (11) and (12), we obtain the dimensionless equations,

$$(NF_{\eta})_{\eta} + \phi [fF_{\eta} + \chi(1 - F^{2})]$$

$$-P[F_{\bar{t}} - \phi^{-1}\phi_{\bar{t}}(1 - F)] + \alpha \phi S^{2}$$

$$+\phi^{-1}\lambda S_{1}(\bar{x})(1 - G) + MP(1 - F)$$

$$= 2Q\phi (FF_{\bar{x}} - f_{\bar{x}}F_{\eta})$$
(22)

$$(NS_{\eta})_{\eta} + \phi f S_{\eta} - P[S_{\bar{t}} + \phi^{-1}\phi_{\bar{t}}S]$$

$$-\alpha_{1}\phi FS - MPS = 2Q\phi(FS_{\bar{x}} - f_{\bar{x}}S_{\eta})$$

$$\left(\frac{1}{Pr}NG_{\eta}\right)_{\eta} + \phi f G_{\eta} - PG_{\bar{t}}$$

$$+N\left(\frac{u_{e}}{u_{\infty}}\right)^{2} Ec[F_{\eta}^{2} + BS_{\eta}^{2}]$$

$$+PEcM\left(\frac{u_{e}}{u_{\infty}}\right)^{2} (F^{2} + BS^{2} - F)$$

$$= 2Q\phi(FG_{\bar{x}} - f_{\bar{x}}G_{\eta})$$
The boundary conditions become
$$(23)$$

 $F(\bar{x}, 0, \bar{t}) = 0, \quad F(\bar{x}, \infty, \bar{t}) = 1$

 $S(\bar{x}, 0, \bar{t}) = 1$, $S(\bar{x}, \infty, \bar{t}) = 0$ (25) $G(\bar{x},0,\bar{t})=0, \quad G(\bar{x},\infty,\bar{t})=1.$

The skin friction coefficients in the x – and y –directions and the heat transfer coefficient can be written as

$$C_{f}(Re)^{1/2} = \frac{9K_{2}K_{3}^{-1/2}\phi(\bar{t})}{2}\sin\bar{x}N_{w}(F_{\eta})_{w}$$
$$\overline{C_{f}}(Re)^{1/2} = \frac{9K_{2}K_{3}^{-1/2}\phi(\bar{t})}{2}B^{1/2}\sin\bar{x}N_{w}(S_{\eta})_{w}$$
(26)
$$Nu(Re)^{-1/2} = \frac{3K_{2}K_{3}^{-1/2}}{2}(G_{\eta})_{w}$$

where,

$$C_{f} = \frac{2\left[\mu\left(\frac{\partial u}{\partial z}\right)\right]_{w}}{\rho u_{\infty}^{2}}, \overline{C_{f}} = \frac{2\left[\mu\left(\frac{\partial v}{\partial z}\right)\right]_{w}}{\rho u_{\infty}^{2}},$$

$$Nu = \frac{R\left(\frac{\partial T}{\partial z}\right)_{w}}{(T_{\infty} - T_{w})'},$$

$$N_{w} = \frac{1}{a_{1} + a_{2}G_{w}} = \text{constant}$$

$$(27)$$

3. Method of Solution

Quasilinearization is a technique introduced by Bellman and Kalaba [53], that can linearize nonlinear initial boundary value issues and is considered an extension of the Newton Raphson approach in functional space. This approach not only linearizes the original nonlinear equation, but it also gives a series of functions that converge to the nonlinear problem's solution. After quasilinearizing the highly nonlinear equations (22)-(24), the following set of linear partial differential equations are obtained.

$$\begin{aligned} A_{1}^{m}F_{\eta\eta}^{m+1} + A_{2}^{m}F_{\eta}^{m+1} + A_{3}^{m}F^{m+1} + A_{4}^{m}F_{\bar{x}}^{m+1} \\ + A_{5}^{m}G_{\eta}^{m+1} + A_{6}^{m}G^{m+1} + A_{7}^{m}S^{m+1} + A_{8}^{m}F_{\bar{t}}^{m+1} \\ &= A_{9}^{m} \\ B_{1}^{m}S_{\eta\eta}^{m+1} + B_{2}^{m}S_{\eta}^{m+1} + B_{3}^{m}S^{m+1} + B_{4}^{m}S_{\bar{x}}^{m+1} \\ + B_{5}^{m}G_{\eta}^{m+1} + B_{6}^{m}G^{m+1} + B_{7}^{m}F^{m+1} + B_{8}^{m}S_{\bar{t}}^{m+1} \\ &= B_{9}^{m} \\ C_{1}^{m}G_{\eta\eta}^{m+1} + C_{2}^{m}G_{\eta}^{m+1} + C_{3}^{m}G^{m+1} + C_{4}^{m}G_{\bar{x}}^{m+1} \\ + C_{5}^{m}F_{\eta}^{m+1} + C_{6}^{m}F^{m+1} + C_{7}^{m}S_{\eta}^{m+1} + C_{8}^{m}S^{m+1} \\ + C_{9}^{m}G_{\bar{t}}^{m+1} = C_{10}^{m} \end{aligned}$$
(28)

Here, the superscript m and m + 1 denote the previous and current iterations and the coefficients are as follows

$$\begin{split} A_{1} &= N \\ A_{2} &= \phi f + 2Q\phi f_{\bar{x}} - E_{2}N^{2}G_{\eta} \\ A_{3} &= -2\phi\chi F - P\phi^{-1}\phi_{\bar{t}} - MP - 2Q\phi F_{\bar{x}} \\ A_{4} &= -2Q\phi F \\ A_{5} &= -E_{2}N^{2}F_{\eta} \\ A_{6} &= -\phi^{-1}\lambda S_{1} + 2E_{2}^{2}N^{3}F_{\eta}G_{\eta} - E_{2}N^{2}F_{\eta\eta} \\ A_{7} &= 2\alpha\phi S \\ A_{8} &= -P \\ A_{9} &= -\phi\chi(1 + F^{2}) - P\phi^{-1}\phi_{\bar{t}} + \alpha\phi S^{2} - MP \\ -2Q\phi FF_{x} - E_{2}N^{2}F_{\eta}G_{\eta} + 2E_{2}^{2}N^{3}F_{\eta}G_{\eta}G \\ -E_{2}N^{2}F_{\eta\eta}G - \phi^{-1}\lambda S_{1} \\ B_{1} &= N \\ B_{2} &= \phi f + 2Q\phi f_{\bar{x}} - E_{2}N^{2}G_{\eta} \\ B_{3} &= -P\phi^{-1}\phi_{\bar{t}} - \alpha_{1}\phi F - MP \\ B_{4} &= -2Q\phi F \\ B_{5} &= -E_{2}N^{2}S_{\eta} \\ B_{6} &= 2E_{2}^{2}N^{3}S_{\eta}G_{\eta} - E_{2}N^{2}S_{\eta\eta} \\ B_{7} &= -\alpha_{1}\phi S - 2Q\phi S_{\bar{x}} \\ B_{8} &= -P \\ B_{9} &= -\alpha_{1}\phi SF - 2Q\phi FS_{\bar{x}} - E_{2}N^{2}S_{\eta}G_{\eta} \\ + 2E_{2}^{2}N^{3}S_{\eta}G_{\eta}G - E_{2}N^{2}S_{\eta\eta}G \\ C_{1} &= \frac{N}{Pr} \\ C_{2} &= \phi f + 2Q\phi f_{\bar{x}} + 2\left(E_{4}N - \frac{E_{2}N^{2}}{Pr}\right)G_{\eta} \\ C_{3} &= -E_{2}N^{2}Ec\left(\frac{u_{e}}{u_{\infty}}\right)^{2}(F_{\eta}^{2} + BS_{\eta}^{2}) \\ + 2\left(-E_{2}E_{4}N^{2} + \frac{E_{2}^{2}N^{3}}{Pr}\right)G_{\eta}^{2} + \left(E_{4}N - \frac{E_{2}N^{2}}{Pr}\right)G_{\eta\eta} \\ C_{4} &= -2Q\phi F \\ C_{5} &= 2NEc\left(\frac{u_{e}}{u_{\infty}}\right)^{2}(2F - 1) - 2Q\phi G_{\bar{x}} \\ C_{7} &= 2NEc\left(\frac{u_{e}}{u_{\infty}}\right)^{2}BS \\ C_{9} &= -P \\ C_{10} &= G_{\eta}^{2}\left(E_{4}N - \frac{E_{2}N^{2}}{Pr}\right) + C_{3}G - 2Q\phi FG_{\bar{x}} \\ + NEc\left(\frac{u_{e}}{u_{\infty}}\right)^{2}(F_{\eta}^{2} + BS_{\eta}^{2}) + PEcM\left(\frac{u_{e}}{u_{\infty}}\right)^{2}(F^{2} + BS^{2}) \end{split}$$

All the coefficients above are known values from *m*th iteration. With step sizes $\Delta \eta$, $\Delta \bar{x}$, $\Delta \bar{t}$ in their respective directions, the linearized partial differential equations in (28) are discretized using central difference scheme in η direction and backward difference scheme in \bar{x} , \bar{t} directions and the linear difference equations are written in the following matrix form [54]

$$X_{i,j,k}\zeta_{i,j-1,k} + Y_{i,j,k}\zeta_{i,j,k} + Z_{i,j,k}\zeta_{i,j+1,k} = W_{i,j,k}, 2 \le j \le \bar{J}$$
(29)

where the coefficient matrices are as follows

$$\begin{split} X_{j} &= \begin{bmatrix} A_{1} - A_{2} \frac{\Delta \eta}{2} & 0 & -A_{5} \frac{\Delta \eta}{2} \\ 0 & B_{1} - B_{2} \frac{\Delta \eta}{2} & -B_{5} \frac{\Delta \eta}{2} \\ -C_{5} \frac{\Delta \eta}{2} & -C_{7} \frac{\Delta \eta}{2} & C_{1} - C_{2} \frac{\Delta \eta}{2} \end{bmatrix} \\ Y_{j} \\ &= \begin{bmatrix} -2A_{1} + H_{1} \Delta \eta^{2} & A_{7} \Delta \eta^{2} & A_{6} \Delta \eta^{2} \\ B_{7} \Delta \eta^{2} & -2B_{1} + H_{2} \Delta \eta^{2} & B_{6} \Delta \eta^{2} \\ C_{6} \Delta \eta^{2} & C_{8} \Delta \eta^{2} & -2C_{1} + H_{3} \Delta \eta^{2} \end{bmatrix} \\ Z_{j} &= \begin{bmatrix} A_{1} + A_{2} \frac{\Delta \eta}{2} & 0 & A_{5} \frac{\Delta \eta}{2} \\ 0 & B_{1} + B_{2} \frac{\Delta \eta}{2} & B_{5} \frac{\Delta \eta}{2} \\ C_{5} \frac{\Delta \eta}{2} & C_{7} \frac{\Delta \eta}{2} & C_{1} + C_{2} \frac{\Delta \eta}{2} \end{bmatrix} \\ W_{j} &= \begin{bmatrix} \left(A_{9} + \frac{A_{4}}{A\bar{x}}F_{i-1,j,k} + \frac{A_{8}}{A\bar{t}}F_{i,j,k-1}\right)\Delta \eta^{2} \\ \left(B_{9} + \frac{B_{4}}{A\bar{x}}S_{i-1,j,k} + \frac{B_{8}}{A\bar{t}}S_{i,j,k-1}\right)\Delta \eta^{2} \\ \left(C_{10} + \frac{C_{4}}{A\bar{x}}G_{i-1,j,k} + \frac{C_{9}}{A\bar{t}}G_{i,j,k-1}\right)\Delta \eta^{2} \end{bmatrix} \\ \zeta_{i,j,k} &= \begin{bmatrix} F_{i,j,k} \\ S_{i,j,k} \\ G_{i,j,k} \end{bmatrix} \end{split}$$

where

$$H_1 = A_3 + \frac{A_4}{\Delta \bar{x}} + \frac{A_8}{\Delta \bar{t}}, H_2 = B_3 + \frac{B_4}{\Delta \bar{x}} + \frac{B_8}{\Delta \bar{t}}$$
$$H_3 = C_3 + \frac{C_4}{\Delta \bar{x}} + \frac{C_9}{\Delta \bar{t}}.$$

The system of tridiagonal blocks (29) is then solved by using Varga's algorithm [55] for ζ in η direction, which is discretized into \overline{J} subintervals, with fixed $\overline{x}, \overline{t}$ and the forward marching continues in \overline{x} direction. The above-mentioned process repeats for the subsequent steps in \overline{t} direction.

The convergence of the solution at each step is assumed to be achieved when the maximum absolute difference between the current and previous iterations is less than the tolerance value, which is set at 10^{-4} . Here, the step sizes are taken as $\Delta \eta = 10^{-2}$, $\Delta \bar{x} = 5 \times 10^{-4}$ and $\Delta \bar{t} = 10^{-2}$. η_{∞} is considered to be 6.

4. Results and Discussion

The precision of our study is ensured by comparing the obtained solutions with those available in the literature in both steady and unsteady cases.

In the case of steady flow, the effect of rotation *B* on the skin friction parameters $[(F_{\eta})_{w}, -(S_{\eta})_{w}]$ and the heat transfer parameter, $[(G_{\eta})_{w}]$ are presented in Figure 2, and the effect of mixed convection parameter λ on skin friction coefficient in *x*-direction $[C_{f}(Re)^{1/2}]$ is shown in Figure 3.

The results are compared with those of Roy and Saikrishnan [14] and Chen et al. [29], respectively.

Also, in the case of unsteady flow, the impact of MHD parameter M on $C_f(Re)^{1/2}$ at times $\bar{t} = 0, 2$ are presented in Figure 4 and are compared with those of Sathyakrishna et al. [40]. All the above-mentioned studies agree with our results.

The variations in the skin friction coefficients in the x, y –directions and the heat transfer coefficient $\left[C_{f}(Re)^{1/2}, \ \overline{C_{f}}(Re)^{1/2}, \ Nu(Re)^{-1/2}\right]$ at various streamwise locations due to the MHD parameter M $T_{\infty} = 18.7^{\circ}\text{C}, \ \Delta T_{w} = 10^{\circ}\text{C}, B = 1, \ \lambda = 20, A =$ with 0, Ec = 0 are presented in Figure 5 and Figure 6 for both steady and unsteady cases. From the figures, $C_f(Re)^{1/2}$ enhances from zero, hits maximum value and then declines as \bar{x} increases. With an increase in M and \bar{t} , both $C_f(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ increase, whereas the effect is just the opposite on $\overline{C_f}(Re)^{1/2}$. The reason for this is the magnetic field B_0 induces a magnetic force which in turn creates a supporting force in the meridian direction and an opposing force in the rotational direction. Hence, increasing M accelerates the flow in x –direction and decelerates the flow in y –direction and thus resulting in the enhancement of $C_f(Re)^{1/2}$, $Nu(Re)^{-1/2}$ and reduction in $\overline{C_f}(Re)^{1/2}$. For fixed M, $Nu(Re)^{-1/2}$ decreases monotonically as \bar{x} increases. In the case of steady flow, the significance of the MHD parameter is not pronounced on $C_f(Re)^{1/2}$ and $Nu(Re)^{-1/2}$. However, the effect becomes significant with time \bar{t} .



Figure 2. Comparison of the velocity profiles in $x, y - directions and temperature profile for a steady flow with those of Roy and Saikrishnan [14] where <math>T_{\infty} = 18.7^{\circ}$ C, $\Delta T_w = 20^{\circ}$ C, constant viscosity and Prandtl number



x -direction with those of Chen et al. [29] where $T_{\infty} = 18.7^{\circ}$ C, $\Delta T_{w} = 10^{\circ}$ C, constant viscosity and Prandtl number



Figure 4. Comparison of the skin friction parameter in the x -direction for an unsteady flow with those of Sathyakrishna et al. [40] where $T_{\infty} = 18.7^{\circ}$ C, $\Delta T_{w} = 10^{\circ}$ C



Figure 5. Effect of the MHD parameter *M* on the skin friction coefficients in *x*, *y* –directions for $\lambda = 20, B = 1$



Figure 6. Effect of the MHD parameter *M* on the heat transfer coefficient for $\lambda = 20, B = 1$

Figure 7 and Figure 8 depict the influence of the mixed convection parameter λ on $C_f(Re)^{1/2}$, $\overline{C_f}(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ over time for $T_{\infty} = 18.7^{\circ}$ C, $\Delta T_w = 10^{\circ}$ C, B = 1, M = 1, A = 0, Ec = 0. The presence of mixed convection parameter $\lambda \neq 0$ signifies favorable pressure gradient. This results in thinning of momentum and temperature boundary layers. As a consequence, both $C_f(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ increase and $\overline{C_f}(Re)^{1/2}$ decreases as λ increases at both times $\overline{t} = 0, 2$. It is to be noted that the significance of λ is more prominent on $C_f(Re)^{1/2}$ than on $\overline{C_f}(Re)^{1/2}$ because there is no explicit dependence of the mixed convection parameter λ in equation (23).

Figure 9 and Figure 10 show the impact of rotation parameter B on $C_f(Re)^{1/2}$, $\overline{C_f}(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ for $T_{\infty} = 18.7^{\circ}$ C, $\Delta T_{w} = 10^{\circ}$ C, M = 1, $\lambda = 10$, A = 0, Ec = 0. It is found that increasing rotation parameter B results in an increase of $C_f(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ and decrease of $\overline{C_f}(Re)^{1/2}$ at both $\overline{t} = 0$ and 2. This is because the fluid entering in the axial direction has been forced outward in the rotational direction due to the centrifugal force and has been replaced by the cooler fluid from the normal direction. This results in accelerating the fluid flow in the axial direction and contracting the thickness of momentum boundary layer in that direction as well as the thickness of the thermal boundary layer. Meanwhile, in the rotational direction, the momentum boundary layer thickens. Also, the effect of *B* on $Nu(Re)^{-1/2}$ is found to be small since *B* affects it indirectly.

For the steady flow, $\overline{C_f}(Re)^{1/2}$ vanishes while $C_f(Re)^{1/2}$ does not. As *B* increases, the point of vanishing skin friction coefficient in *y*-direction moves slightly downwards, indicating an ordinary separation. It is also observed that $C_f(Re)^{1/2}$ vanishes for B > 0, $\overline{t} > 0$, and the point of vanishing skin friction in that direction moves upstream as *B* increases. However, this does not imply separation since it is unsteady.



Figure 7. Effect of the mixed convection parameter λ on the skin friction coefficients in *x*, *y* –directions for M = 1, B = 1



Figure 8. Effect of the mixed convection parameter λ on the heat transfer coefficient for M = 1, B = 1



Figure 9. Effect of the rotation parameter *B* on the skin friction coefficients in *x*, *y* –directions for $M = 1, \lambda = 10$



The impact of the viscous dissipation parameter *Ec* on $Nu(Re)^{-1/2}$ for A = 0, M = 1, $\lambda = 2$, B = 1 has been shown in Figure 11. The heat transfer coefficient $Nu(Re)^{-1/2}$ decreases for the change of values of *Ec* from 0 to -0.1 in both steady and unsteady cases. At $\bar{x} = 1.5$, the percentage decrease of $Nu(Re)^{-1/2}$ is 129% when $\bar{t} = 0$ and 413% at $\bar{t} = 2$ as *Ec* changes from 0 to -0.1. Also, the occurrence of negative $Nu(Re)^{-1/2}$ is physically simulated by the reversal of heat transfer direction.

The reason for this can be seen from the temperature profile *G* at $\bar{x} = 1.5$ depicted in Figure 12. For $Ec \neq 0$ and $\bar{t} = 2$, the temperature *G* gets below zero near the wall. This is because nonzero *Ec* emphasizes the presence of the viscous dissipation and *M* too being nonzero brings on joule heating in the

energy equation. Due to the impact of these two heating, the fluid near the wall heats up and its temperature becomes more than T_w , although originally T_w was higher. This results in the wall being heated up instead of being cooled and hence the heat transfer reversal observed in Figure 11. However, such a phenomenon is not observed in the steady case. *Ec* does not show much of a difference in the skin friction coefficients in x, y –directions as well as the velocity profiles. Hence, the corresponding figures are omitted in this paper.

Figures 13-16 show the influence of non-uniform mass transfer on $C_f(Re)^{1/2}$, $\overline{C_f}(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ for $\lambda = 0.5$, B = 1 and M = 0.5, at $\overline{t} = 0$ and $\overline{t} = 2$. The effect of suction/injection is examined through two slots $[\bar{x}_0, \bar{x}_0^*]$, one at [0.5,1] and the other at [1.25,1.75], but not simultaneously. In the case of slot suction (A > A)0), as the slot starts, $C_f(Re)^{1/2}$ and $Nu(Re)^{-1/2}$ increase and hit their maximum before the slot's end. Contrastingly, $\overline{C_f}(Re)^{1/2}$ decreases as the slot starts and hits its minimum before the slot's end. As the suction parameter increases, the fluid at the sphere's surface, which has low velocity, is sucked through the slot $[\bar{x}_0, \bar{x}_0^*]$ and is replaced by the fluid in the subsequent layers with comparatively higher velocity. This augments the velocity gradients in both x and y –directions at the wall $(F_{\eta}, -S_{\eta})_{w}$ and thus resulting in increasing $C_f(Re)^{1/2}$ and decreasing $\overline{C_f(Re)^{1/2}}$.



Figure 11. Effect of the viscous dissipation parameter *Ec* on the heat transfer coefficient for $\lambda = 2, M = 1, B = 1$



Figure 12. Effect of the viscous dissipation parameter *Ec* on the temperature profile at $\bar{x} = 1.5$ for $\lambda = 2, M = 1, B = 1$



Figure 13. Effect of the non-uniform slot suction *A* on the skin friction coefficients in *x*, *y* –directions for $\lambda = 0.5$, M = 0.5, B = 1, slots at $\bar{x}_0 = 0.5, 1.25$



Figure 14. Effect of the non-uniform slot suction *A* on the heat transfer coefficient for $\lambda = 0.5$, M = 0.5, B = 1, slots at $\bar{x}_0 = 0.5$, 1.25



Figure 15. Effect of the non-uniform slot injection *A* on the skin friction coefficients in *x*, *y* –directions for $\lambda = 0.5$, M = 0.5, B = 1, slots at $\bar{x}_0 = 0.5$, 1.25



Figure 16. Effect of the non-uniform slot injection *A* on the heat transfer coefficient for $\lambda = 0.5, M = 0.5, B = 1$, slots at $\bar{x}_0 = 0.5, 1.25$

Moreover, since the fluid being sucked is warmer than the adjacent layers, the more the suction, the steeper the temperature gradient at the wall and hence $Nu(Re)^{-1/2}$ is enhanced.

The slot injection's (A < 0) effect on skin friction and heat transfer coefficients is qualitatively opposite to that of suction in the slot region. In all the above cases, regardless of Α, the coefficients $\left[C_{f}(Re)^{1/2}, -\overline{C_{f}}(Re)^{1/2}, Nu(Re)^{-1/2}\right]$ are enhanced as \overline{t} increases and the impact is more pronounced in the unsteady case, since the flow is accelerating with \bar{t} . For the steady case $(\bar{t} = 0)$, the suction/injection doesn't impact the zero skin frictions in both directions. However, when $\bar{t} > 0$, the point of zero skin friction in x –direction moves downstream with an increase in suction parameter (A > 0). The slot movement in the downstream direction from [0.5,1] to [1.25,1.75] helps the vanishing point of $C_f(Re)^{1/2}$ move further downstream. Meanwhile, the opposite effect is seen with an enhancement in the injection parameter. It should be emphasized here that zero skin friction in only one direction/both directions does not imply the ordinary/singular separation as the flow considered here is unsteady.

Conclusion

An unsteady MHD mixed convection boundary layer flow problem over a geometry of rotating sphere has been solved numerically, and the observations are as follows.

- The MHD parameter (M) affects the skin friction coefficient in x –direction and heat transfer coefficient noticeably in the unsteady case than it does in the steady case for fixed non-zero values of rotation and mixed convection parameters.
- The mixed convection parameter (λ) is found to have a prominent effect on the skin friction coefficient in the x-direction and the heat transfer coefficient than the skin friction coefficient in the y –direction, in both steady and unsteady cases.
- For non-zero values of rotation parameter B, an ordinary separation is noted in the steady case as $\overline{C_f}(Re)^{1/2}$ vanishes while $C_f(Re)^{1/2}$ does not. It is observed that $C_f(Re)^{1/2}$ vanishes for B > 0, $\overline{t} > 0$, and that point of vanishing moves upstream as the rotation parameter increases.
- At both times $\bar{t} = 0$ and 2, the more the magnitude of viscous dissipation parameter (Ec) the less the heat transfer coefficient as a result of heating due to viscous and joule heating effects. Moreover, the unsteadiness results in drastic decrement in the heat transfer coefficient as dissipation increases.
- The temperature drops below zero in the vicinity of the sphere's surface in the unsteady case, indicating the fluid near the surface of the sphere getting warmer instead of colder.

For fixed non-zero values of B, M, λ and $\overline{t} > 0$, non-uniform slot suction or slot movement helps the vanishing skin friction in x –direction to move slightly downstream, whereas the injection shows the opposite effect.

Nomenciature	
A	Dimensionless mass transfer parameter
B_0	Magnetic field strength (T)
В	Dimensionless rotation parameter
c_p	Specific heat at constant pressure $(kJ \cdot kg^{-1} \cdot K^{-1})$
C_f	Skin friction coefficient in the x –direction
C_f	Skin friction coefficient in the y –direction
Ec	Eckert number (viscous dissipation parameter)
f	Dimensionless stream function
f _w F	Surface mass transfer distribution Dimensionless velocity component in the x –direction
g	Gravity $(m \cdot s^{-2})$
G	Dimensionless temperature
Gr	Grashof number
k	Thermal conductivity $(W \cdot m^{-1} \cdot K^{-1})$
М	MHD parameter
Ν	μ/μ_{∞} Viscosity ratio
Nu	Nusselt number
Pr	Prandtl number
r	Radius of the section normal to the axis of the sphere (m)
R	Radius of the sphere (m)
Re	Reynolds number
S	Dimensionless velocity component in the y –direction
t	Dimensional time (<i>s</i>)
Ī	Dimensionless time
Т	Temperature (K)
u, v, w U	Dimensional velocity components in <i>x</i> , <i>y</i> , <i>z</i> –directions, respectively $(m \cdot s^{-1})$ Steady state velocity at the boundary layer's edge $(m \cdot s^{-1})$
x, y, z	Dimensional meridional, azimuthal and normal distances, respectively (<i>m</i>)
\bar{x}	Dimensionless meridional distance
$ar{x}_0$, $ar{x}_0^*$	Ends of slot
Greek Sy	mbols
χ	Dimensionless pressure gradient
β	Volumetric coefficient of thermal expansion (K^{-1})
$\Delta \eta, \Delta x, \\ \Delta \overline{t}$	Step sizes in η , x – and t –directions, respectively
 η, ξ	Transformed coordinates
e	Constant used in the continuous function
1 1	of time Mixed convection normator
л 11	Mixed convection parameter Dynamic viscosity (k_{a}, m^{-1}, s^{-1})
μ	Dynamic viscosity (kg · m · S)

- v Kinematic viscosity $(m^2 \cdot s^{-1})$
- ρ Density $(kg \cdot m^{-3})$
- σ Electrical conduction ($Ω^{-1} \cdot m^{-1}$)
- Ψ Dimensional stream function $(m^2 \cdot s^{-1})$
- $\phi(\bar{t})$ Continuous function of time
- Ω Angular velocity ($rad \cdot s^{-1}$)
- $\omega^* \qquad \text{Slot length parameter} \\$

Subscripts

- *e* Conditions at the edge of boundary layer
- *w* Conditions at the surface of the sphere
- ∞ Conditions in the free stream
- x, z, \overline{x} , Partial derivatives with respect to these
- *τ̄*, ξ, η variables

Acknowledgements

The authors are thankful to the reviewers for their valuable comments. The first author would like to thank National Institute of Technology Tiruchirappalli for supporting through an institute fellowship.

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